

A COMPUTER PROGRAM FOR EVALUATING THE HYDRODYNAMIC PARAMETERS OF A MACROMOLECULE IN SOLUTION FOR ANY GIVEN VALUE OF ITS AXIAL DIMENSIONS*

STEPHEN E. HARDING

Department of Biochemistry, Bristol University, Bristol, England.

(Received 27 January 1981; in revised form 11 May 1981; received for publication 1 June 1981)

Abstract—A FORTRAN IV algorithm is given for determining the hydrodynamic parameters of a macromolecule in solution for any specified value of the two axial ratios ($a/b, b/c$) of the equivalent tri-axial ellipsoid model of semi-axes $a \geq b \geq c$ for its gross conformation.

Ellipsoid model Axial ratios Elliptic integrals Myoglobin

1. INTRODUCTION

The ellipsoid of revolution (i.e. an ellipsoid with two equal axes) has up to now been the most popular model for the gross conformation of biological macromolecules in solution. This has been until recently the most general model available for which it is possible to predict from a macromolecule's known hydrodynamic properties the shape in terms of its axial ratio without assumptions concerning hydrodynamic volume.

Although prediction of the two axial ratios from knowledge of the hydrodynamic parameters of the more general tri-axial ellipsoid presents great problems [1] the converse is not so difficult: it is relatively easy to predict the hydrodynamic parameters corresponding to a given value of the axial ratios. This would have immediate application in, for example, predicting the properties of proteins whose dimensions are known from crystallographic studies.

This paper presents a program which calculates the hydrodynamic parameters for specified values of the two axial ratios ($a/b, b/c$) of a general ellipsoid, where a, b, c are the three semi-axes and $a \geq b \geq c$. For an oblate ellipsoid of revolution $a = b$ and for a prolate ellipsoid $b = c$.

2. THE HYDRODYNAMIC SHAPE PARAMETERS

These can be divided into three basic classes:

(i) The viscosity increment v . This is based on the effect of the dissolved macromolecule on the bulk motion of the fluid when a shear gradient is applied.

(ii) The translational frictional ratio f/f_o . This concerns the resistance to motion of a macromolecule through its solution when some form of external force (e.g. centrifugal field, diffusion gradient) is applied.

(iii) The rotational frictional ratios ζ_i/ζ_o ($i = a, b, c$; "o" refers to the corresponding coefficient for a hydrated sphere of the same volume) concerns the disorientating effect on the macromolecule by the local Brownian motion of the surrounding solvent molecules. Related to these are three dielectric dispersion relaxation ratios ρ_i/ρ_o corresponding to rotation of a

*This work was completed whilst the author was at the Department of Biochemistry, Leicester University, England.

particular axis about the other two, a harmonic mean relaxation time ratio τ_h/τ_o , five fluorescence anisotropy relaxation time ratios T_j/T_o ($j = 1 \rightarrow 5$) and two reduced birefringence decay constants, θ_+^{red} and θ_-^{red} .

All the above parameters require for their experimental determination a knowledge of the swollen macromolecular volume due to solvent association or "swelling" in solution. This can be eliminated by combining pairs of the above parameters to give "derived" shape parameters which are volume independent: β , R , δ_i , γ_i , μ_i , Ψ , Λ , δ_+ , δ_- , γ_+ and γ_- . Each of these derived parameters is defined in Table 1 in terms of the parameters listed in Sections (i)–(iii). The relation of all these parameters with axial ratio of a general ellipsoid ($a \geq b \geq c$), is given in Table 1. Relations with experimental parameters have been given in [1, 2].

Table 1. Hydrodynamic parameters: mathematical formulation for tri-axial ellipsoids

Function	Mathematical formulation	Computer symbol
v	$\frac{1}{abc} \left\{ \frac{4(\alpha_7 + \alpha_8 + \alpha_9)}{15(\alpha_8\alpha_9 + \alpha_9\alpha_7 + \alpha_7\alpha_8)} \right.$ $+ \frac{1}{5} \left(\frac{\alpha_2 + \alpha_3}{\alpha_4(b^2\alpha_2 + c^2\alpha_3)} + \frac{\alpha_3 + \alpha_1}{\alpha_5(c^2\alpha_3 + a^2\alpha_1)} + \frac{\alpha_1 + \alpha_2}{\alpha_6(a^2\alpha_1 + b^2\alpha_2)} \right)$ $* \left. - \frac{1}{5} \left(\frac{\left[\frac{a^2 - b^2}{a^2\alpha_1 + b^2\alpha_2} + \frac{b^2 - c^2}{b^2\alpha_2 + c^2\alpha_3} + \frac{c^2 - a^2}{c^2\alpha_3 + a^2\alpha_1} \right]^2}{\left[\frac{a^2 + b^2}{a^2\alpha_1 + b^2\alpha_2} + \frac{b^2 + c^2}{b^2\alpha_2 + c^2\alpha_3} + \frac{c^2 + a^2}{c^2\alpha_3 + a^2\alpha_1} \right]} \right) \right\}$	NU
f/f_o	$2/\{(abc)^{1/3}\alpha_{10}\}$	F
ζ_a/ζ_o	$2(b^2 + c^2)/\{3abc(b^2\alpha_2 + c^2\alpha_3)\}$	CA
ζ_b/ζ_o	$2(c^2 + a^2)/\{3abc(c^2\alpha_3 + a^2\alpha_1)\}$	CB
ζ_c/ζ_o	$2(a^2 + b^2)/\{3abc(a^2\alpha_1 + b^2\alpha_2)\}$	CC
ρ_a/ρ_o	$2 \left\{ \frac{\zeta_o}{\zeta_b} + \frac{\zeta_o}{\zeta_c} \right\}$	RHOA
ρ_b/ρ_o	$2 \left\{ \frac{\zeta_o}{\zeta_c} + \frac{\zeta_o}{\zeta_a} \right\}$	RHOB
ρ_c/ρ_o	$2 \left\{ \frac{\zeta_o}{\zeta_a} + \frac{\zeta_o}{\zeta_b} \right\}$	RHOC
τ_h/τ_o	$3 \left\{ \frac{\rho_o}{\rho_a} + \frac{\rho_o}{\rho_b} + \frac{\rho_o}{\rho_c} \right\}$	TAU
$\theta_{\pm}^{\text{red}}$	$\frac{abc}{12} \left\{ \left(\frac{1}{Q_a} + \frac{1}{Q_b} + \frac{1}{Q_c} \right) \pm \left[\left(\frac{1}{Q_a^2} + \frac{1}{Q_b^2} + \frac{1}{Q_c^2} \right) - \left(\frac{1}{Q_a Q_b} + \frac{1}{Q_b Q_c} + \frac{1}{Q_c Q_a} \right) \right]^{1/2} \right\}$	θ_+^{red} : THETA + or TPLS θ_-^{red} : THETA - or TMNS
$\ddagger T_1/T_o$	$1/(X_4 + X_1)$	T_1
T_2/T_o	$1/(X_4 + X_2)$	T_2
T_3/T_o	$1/(X_4 + X_3)$	T_3
T_4/T_o	$1/(6X_4 - 2X_5)$	T_4
T_5/T_o	$1/(6X_4 + 2X_5)$	T_5
$\S\beta$	$\frac{N_A^{1/3}}{(16200\pi^2)^{1/3}} \frac{v^{1/3}}{f/f_o}$	BETA
R	$\frac{2}{v} \left(1 + \left[\frac{f}{f_o} \right]^3 \right)$	R
δ_i	$v\zeta_o/\zeta_i$ ($i = a, b, c$)	DELA, DELB, DELC
γ_i	$(f/f_o)^3 \rho_o/\rho_i$	GAMMA A, GAMMA B, GAMMA C
μ_i	$(f_o/f)(\zeta_i/\zeta_o)^{1/3}$	MUA, MUB, MUC

Ψ	$(f/f_o)(\tau_o/\tau_h)^{1/3}$	PSI
Λ	$v\tau_o/\tau_h$	LAMBDA
δ_+	$6v\theta_+^{red}$	DPLS or DELTA +
δ_-	$6v\theta_-^{red}$	DMNS or DELTA -
γ_+	$6(f/f_o)^3\theta_+^{red}$	GPLS or GAMMA +
γ_-	$6(f/f_o)^3\theta_-^{red}$	GMNS or GAMMA -

* This term is negligible for globular particles (axial ratios < 3). [8]

$$\dagger Q_a = \frac{b^2 + c^2}{b^2\alpha_2 + c^2\alpha_3}, \quad Q_b = \frac{c^2 + a^2}{c^2\alpha_3 + a^2\alpha_1}, \quad Q_c = \frac{a^2 + b^2}{a^2\alpha_1 + b^2\alpha_2}.$$

$$\ddagger X_1 = \frac{1}{2} \left\{ \frac{\rho_o}{\rho_b} + \frac{\rho_o}{\rho_c} - \frac{\rho_o}{\rho_a} \right\}, \quad X_2 = \frac{1}{2} \left\{ \frac{\rho_o}{\rho_c} + \frac{\rho_o}{\rho_a} - \frac{\rho_o}{\rho_b} \right\}, \quad X_3 = \frac{1}{2} \left\{ \frac{\rho_o}{\rho_a} + \frac{\rho_o}{\rho_b} - \frac{\rho_o}{\rho_c} \right\}$$

$$X_4 = \frac{1}{3}(X_1 + X_2 + X_3), \quad X_5 = \{X_1^2 + X_2^2 + X_3^2 - X_1X_2 - X_2X_3 - X_3X_1\}^{1/2}.$$

§ N_A = Avogadro's Number. In the program β is given $\times 10^{-6}$.

3. COMPUTATIONAL METHOD

All the parameters involve an elliptic integral of the form

$$\int_0^\infty f(x) dx$$

(Appendix). There is at present no packaged or published numerical routine available for integrals of this type; only routines of the form

$$\int_A^B f(x) dx$$

where A can be zero but B must have finite value, specifiable by the user. One such routine used in this program is the Oxford Numerical Algorithms Group's FORTRAN IV NAG DØ1 AGF[3] which uses an internal subdivision strategy developed by Oliver [4] and based on Clenshaw-Curtis quadrature [5].

A satisfactory value for B was determined by using successively higher values until the integral converged to a limiting value. The number of the interval subdivisions (MAXDIV) is also specifiable by the user; the maximum number of fifty was used. The package also estimates the error on the integrals [6]. If this error is greater than the maximum allowable error specifiable by the user the routine will stop and print an error message. The maximum allowable error specified was 1.0×10^{-8} (equivalent to $\sim 0.001\%$). The integrands are specified as an external function (Table 3) and the integrals α_k ($k = 1 \rightarrow 10$) when calculated are stored and called up in the calculation of each shape parameter in the main program, partly shown in Table 2.

4. RESULTS

The results of a sample run for values of (a/b , b/c) of (1.5, 1.5) are given in Table 4. Provided the axial dimensions are known, for example, from X-ray crystallography, the hydrodynamic parameters for any protein can therefore be obtained, provided the general ellipsoid represents a reasonable model for the macromolecular shape, an assumption generally valid for globular proteins. These predicted parameters can be compared with experimentally determined parameters and deductions can be made about whether the crystallographic shape is the same in solution. For example, the crystallographically determined dimensions of myoglobin, a protein of biomedical importance—serving as a reserve supply of oxygen in the muscle tissue of mammals—have been given as $43 \times 35 \times 23 \text{ \AA}$ ($a/b = 1.23$, $b/c = 1.52$).

Table 2. Evaluation of the hydrodynamic shape parameters for tri-axial ellipsoids. The WRITE statements at the end of the program have not been included

```

PROGRAM MAIN(INPUT,OUTPUT,TAPE2=INPUT,TAPE3=OUTPUT)
COMMON/PARAM/A,C,NN
EXTERNAL FUN
DIMENSION ALPHA(10)
REAL NU,M,O,P
REAL MUA,MUB,MUC,PSI,N1,N2,RHOA,RHOB,RHOC
C ENTER AS DATA AT THE FOOT OF THE PROGRAM (A/B, B/C)
READ(2,*)N1,N2
NN=J
C COMPUTE THE ELLIPTIC INTEGRALS
DO45 K=1,10
A=N1
B=1.0
C=1.0/N2
NN=NN+1
C SET LIMITS FOR NUMERICAL INTEGRATION (THESE LIMITS
C BELOW HAVE BEEN PREVIOUSLY TESTED FOR CONVERGENCE)
AA=0.0
BB=1000000
IF(NN.EQ.10)BB=500000000
MAXDIV=50
EPS=1.0E-08
ACC=0.0
IFAIL=0
C CALL U. K. "NAG" LIBRARY ROUTINE FOR NUMERICAL EVALUATION
C OF THE INTEGRALS "ALPHA" GIVEN IN THE SUBROUTINE BELOW
CALL D01AGF(AA,BB,FUN,MAXDIV,EPS,ACC,ANS,ERROR,NOFUN,IFAIL)
ALPHA(NN)=ANS
45 CONTINUE
B=1.0
C NOW COMPUTE THE FUNCTION VALUES USING THE STORED INTEGRAL VALUES
X1=(A*A)-(B*B)
X2=(C*C)-(A*A)
X3=(B*B)-(C*C)
Y1=(A*A)+(B*B)
Y2=(C*C)+(A*A)
Y3=(B*B)+(C*C)
Z1=(A*A*ALPHA(1))+(B*B*ALPHA(2))
Z2=(C*C*ALPHA(3))+(A*A*ALPHA(1))
Z3=(B*B*ALPHA(2))+(C*C*ALPHA(3))
EXT=-((1.0/5.0)*(1.0/(A*B*C))*(((X1/Z1)+(X2/Z2)+(X3/Z3))**2.0)
+((Y1/Z1)+(Y2/Z2)+(Y3/Z3)))
NU=(1.0/(A*B*C))*((4.0/15.0)*((ALPHA(7)+ALPHA(8)
+ALPHA(9))/(ALPHA(8)*ALPHA(9)+ALPHA(9)*ALPHA
+(7)+ALPHA(7)*ALPHA(8)))+(1.0/5.0)*(((ALPHA(2)
+ALPHA(3))/(ALPHA(4)*ALPHA(2)+C*C*ALPHA(3)
+)))+((ALPHA(3)+ALPHA(1))/(ALPHA(5)*C*C*ALPHA(3)
+ A*A*ALPHA(1)))+(ALPHA(1)+ALPHA(2))/(ALPHA(6)
+ (A*A*ALPHA(1)+B*B*ALPHA(2))))+EXT
M=(B*B+C*C)/(B*B*ALPHA(2)+C*C*ALPHA(3))
O=(C*C+A*A)/(C*C*ALPHA(3)+A*A*ALPHA(1))
P=(A*A+B*B)/(A*A*ALPHA(1)+B*B*ALPHA(2))
TPLS=((A*B*C)/(12.0))*(((1.0/M)+(1.0/O)+(1.0/P)
+)))+(((1.0/M**2.0)+(1.0/O**2.0)+(1.0/P**2.0))-
+ ((1.0/(M*O)))+(1.0/(O*P)))+(1.0/(P*M)
+ )))**0.5)
TMNS=((A*B*C)/(12.0))*(((1.0/M)+(1.0/O)+(1.0/P)
+)))-(((1.0/M**2.0)+(1.0/O**2.0)+(1.0/P**2.0))-
+ ((1.0/(M*O)))+(1.0/(O*P)))+(1.0/(P*M)
+ )))**0.5)
DPLS=6.0*TPLS*NU
DMNS=6.0*TMNS*NU
F=2.0/((A*B*C)**(1.0/3.0))*ALPHA(10)
R=2.0*(1.0+(F**3.0))/NU
BETA=(1.0/1000000.0)*(((6.0249**((1.0/3.0))*(10.0**((23.0/3.0)
+)))/(16200.0*3.141592654**3.141592654)**(1.0/3.0)))*(NU
+**((1.0/3.0))/F
CA=(2.0/(3.0*A*B*C))*M
CB=(2.0/(3.0*A*B*C))*O
CC=(2.0/(3.0*A*B*C))*P
RHOA=2.0/((1.0/CB)+(1.0/CC))
RHOB=2.0/((1.0/CC)+(1.0/CA))
RHOC=2.0/((1.0/CA)+(1.0/CB))
DELA=NU/CA
DELB=NU/CB
DELC=NU/CC
TAU=3.0/((1.0/CA)+(1.0/CB)+(1.0/CC))
PSI=F*((1.0/TAU)**(1.0/3.0))
V=NU/TAU
ZZ=(1.0/2.0)*(F**3.0)
GAMMAA=ZZ*((1.0/CB)+(1.0/CC))
GAMMAB=ZZ*((1.0/CC)+(1.0/CA))
GAMMAC=ZZ*((1.0/CA)+(1.0/CB))
MUA=(CA**((1.0/3.0)))/F
MUB=(CB**((1.0/3.0)))/F
MUC=(CC**((1.0/3.0)))/F
GPLS=6.0*TPLS*(F**3.0)
GMNS=6.0*TMNS*(F**3.0)
X1=0.5*((1.0/RHOB)+(1.0/RHOC)-(1.0/RHOA))
X2=0.5*((1.0/RHOC)+(1.0/RHOA)-(1.0/RHOB))
X3=0.5*((1.0/RHOA)+(1.0/RHOB)-(1.0/RHOC))
X4=(X1+X2+X3)/3.0
X5=((X1**2.0)+(X2**2.0)+(X3**2.0)-(X1*X2)-(X2*X3)-(X3*X1))
+**0.5
T1=1.0/(X4+X1)
T2=1.0/(X4+X2)
T3=1.0/(X4+X3)
T4=3.0/((6.0*X4)-(2.0*X5))
T5=3.0/((6.0*X4)+(2.0*X5))

```

Table 3. A subroutine for specifying the integrands for numerical integration

```

REAL FUNCTION FUN(X)
COMMON/PARAM/A,C,NN
B=1.0
GOTO(10,20,30,40,50,60,70,80,90,100),NN
10 FUN=1/((A*A+X)**1.5*(B*B+X)**0.5*(C*C+X)**0.5)
RETURN
20 FUN=1/((A*A+X)**0.5*(B*B+X)**1.5*(C*C+X)**0.5)
RETURN
30 FUN=1/((A*A+X)**0.5*(B*B+X)**0.5*(C*C+X)**1.5)
RETURN
40 FUN=1/((A*A+X)**0.5*(B*B+X)**1.5*(C*C+X)**1.5)
RETURN
50 FUN=1/((A*A+X)**1.5*(B*B+X)**0.5*(C*C+X)**1.5)
RETURN
60 FUN=1/((A*A+X)**1.5*(B*B+X)**1.5*(C*C+X)**0.5)
RETURN
70 FUN=X/((A*A+X)**0.5*(B*B+X)**1.5*(C*C+X)**1.5)
RETURN
80 FUN=X/((A*A+X)**1.5*(B*B+X)**0.5*(C*C+X)**1.5)
RETURN
90 FUN=X/((A*A+X)**1.5*(B*B+X)**1.5*(C*C+X)**0.5)
RETURN
100 FUN=1.0/((A*A+X)*(B*B+X)*(C*C+X)**0.5)
RETURN
END
    
```

Table 4. Sample results for a hypothetical protein of axial ratio $(a/b, b/c) = (1.5, 1.5)$. The results are correct to three decimal places

A/B	1.50	B/C	1.50
NU	2.8917		
F	1.0441		
THE TA+		.1626	
THE TA-		.1162	
DEL TA+		2.8212	
DEL TA-		2.0164	
R	1.4788		
BETA	2.1233		
THE 3 ROTATIONAL FRICTIONAL RATIOS:			
CA	.8976		
CB	1.3980		
CC	1.4704		
THE 3 ROTATIONAL RELAXATION TIME RATIOS:			
RHOA	1.4332		
RHOB	1.1147		
RHOC	1.0932		
DELTA A	3.2215		
DELTA B	2.0684		
DELTA C	1.9666		
THE HARMONIC MEAN RELAXATION TIME RATIO:			
TAU	1.1954		
PSI	.9837		
LAMBOA	2.4188		
GAMMA A	.7941		
GAMMA B	1.0210		
GAMMA C	1.0411		
MUA	.9238		
MUB	1.0709		
MUC	1.0891		
GAMMA A+	1.1105		
GAMMA A-	.7937		
FLUORESCENCE ANISOTROPY RELAXATION TIME RATIOS:			
T1	1.0253		
T2	1.2888		
T3	1.3187		
T4	1.4340		
T5	1.0249		

This corresponds to a value of ν , using the above algorithm, of 2.729. That from experiment assuming no swelling is 4.40 ± 0.08 [7], the difference being ascribed either to significant swelling in solution or change of shape.

Prediction of a value for $(a/b, b/c)$ from experimentally measured values for the hydrodynamic parameters is much more difficult; this has been discussed in more detail in an earlier study [1].

5. SUMMARY

The theoretical relationships for the hydrodynamic parameters of a general tri-axial ellipsoid in solution in dominant Brownian motion are now available. A general program is presented which, for any given values of the two axial ratios which define a general ellipsoid, calculates the corresponding hydrodynamic parameters. Thus for any ellipsoidal macromolecules whose dimensions are known from crystallographic studies, the corresponding hydrodynamic parameters can be determined.

REFERENCES

1. S. E. Harding, Modelling biological macromolecules in solution: The general tri-axial ellipsoid, Ph.D. Thesis, Leicester University (1980).
2. S. E. Harding and A. J. Rowe, Modelling biological macromolecules in solution: The general tri-axial ellipsoid, *Biopolymers* (in press).
3. *NAG FORTRAN Library Manual, Mk 7* Vol. 1. Numerical Algorithms Group, Oxford (1978).
4. J. Oliver, A doubly-adaptive Clenshaw-Curtis quadrature method, *Comput. J.* **15**, 141 (1972).
5. C. W. Clenshaw and A. R. Curtis, A method for numerical integration on an automatic computer, *Num. Math.* **2**, 197 (1960).
6. H. O'Hara and F. J. Smith, Error estimation in the Clenshaw-Curtis quadrature formula, *Comput. J.* **11**, 213 (1968).
7. S. E. Harding, Viscosity parameters for myoglobin, *IRCS med. Sci.* **8**, 610 (1980).
8. J. M. Rallison and H. Brenner (private comm.).

About the Author—Dr Harding graduated in Physics and Molecular Biophysics from Oxford in 1976. In 1977 he worked at the Atomic Energy Research Establishment, Harwell, Oxfordshire, receiving an M.Sc. for his work on the improvement in resistance to wear of ion implanted materials. From 1977 to 1980 he researched on modelling macromolecules in solution at the Department of Biochemistry, Leicester University where he received his PhD. He is now working at the University of Bristol on physico-chemical studies of bronchial glycoproteins.

APPENDIX

The elliptic integrals

$$\begin{aligned} \alpha_1 &= \int_0^x \frac{d\lambda}{(a^2 + \lambda)\Delta}; & \alpha_2 &= \int_0^r \frac{d\lambda}{(b^2 + \lambda)\Delta}; & \alpha_3 &= \int_0^r \frac{d\lambda}{(c^2 + \lambda)\Delta} \\ \alpha_4 &= \int_0^r \frac{d\lambda}{(b^2 + \lambda)(c^2 + \lambda)\Delta}; & \alpha_7 &= \int_0^r \frac{\lambda d\lambda}{(b^2 + \lambda)(c^2 + \lambda)\Delta} \\ \alpha_5 &= \int_0^x \frac{d\lambda}{(c^2 + \lambda)(a^2 + \lambda)\Delta}; & \alpha_8 &= \int_0^r \frac{\lambda d\lambda}{(c^2 + \lambda)(a^2 + \lambda)\Delta} \\ \alpha_6 &= \int_0^r \frac{d\lambda}{(a^2 + \lambda)(b^2 + \lambda)\Delta}; & \alpha_9 &= \int_0^r \frac{\lambda d\lambda}{(a^2 + \lambda)(b^2 + \lambda)\Delta} \\ \alpha_{10} &= \int_0^x \frac{d\lambda}{\Delta} & & & & \text{where } \Delta = [(a^2 + \lambda)(b^2 + \lambda)(c^2 + \lambda)]^{1/2}. \end{aligned}$$