

Session overview

10:00 - 10:30	State-of-the-art review - Jon Stammers, Advanced Manufacturing Research Centre
10:30 - 10:50	Gorka Kortaberria – IK4-Tekniker "Integrated volumetric error mapping solution for traceable on-machine tool measurement"
10:50 - 11:10	Tim Rooker – IDC Machining Science "Machining centre performance monitoring with calibrated artefact probing"
11:10 - 11:30	Liam Blunt – University of Huddersfield "In process surface metrology for roll to roll manufacture of printed electronic devices"
11:30 - 11:50	Florian Schwimmer – Alicona "In-line measurements with focus variation as enabler for an autonomous manufacturing cell"
11:50 - 12:20	Darek Ceglarek – University of Warwick "Closed-loop in-process quality improvement: 'Right-first-time' production through digital technologies"
12:20	Lunch

Integrated Metrology for Precision Manufacturing Conference

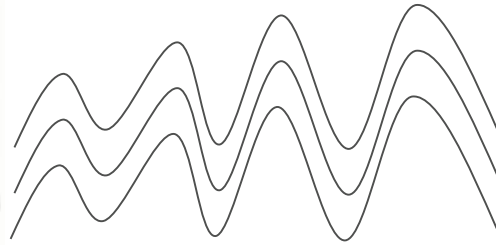
22 - 23 January 2019

Process Monitoring

Dr Jon Stammers

Technical Fellow, Process Monitoring and Control

Process monitoring



Process monitoring

Program

Force

Sound

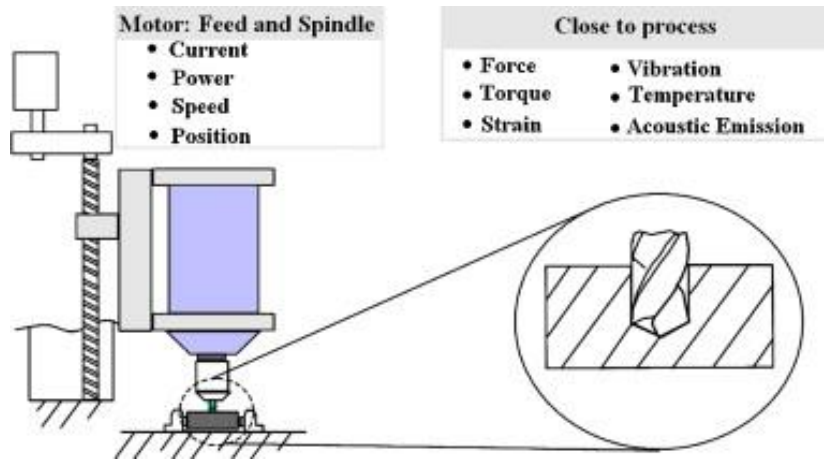
Fluids



Geometry

Temperature

Vibration

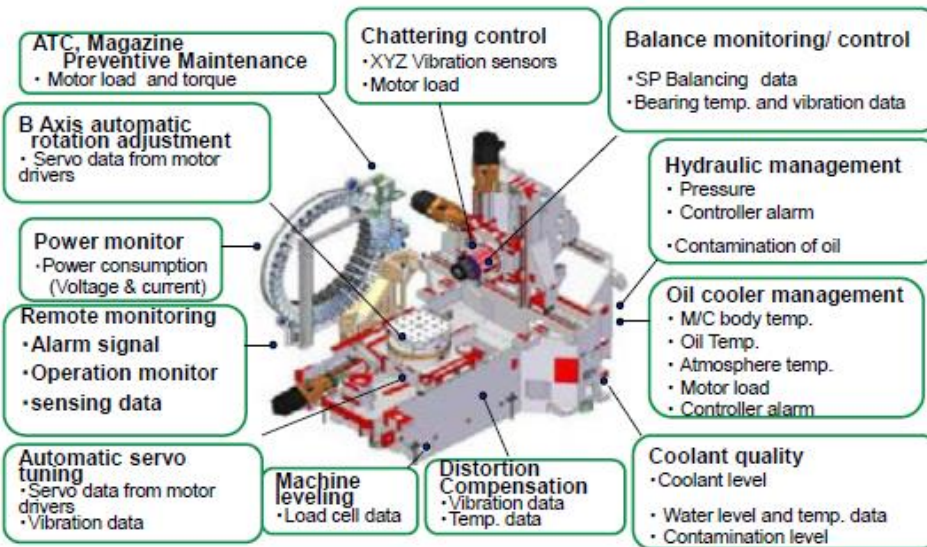


Teti, R., Jemielniak, K., O'Donnell, G., & Dornfeld, D. (2010). CIRP Annals-Manufacturing Technology, 59(2), 717-739

Typical sensor fusion systems

Sensors	Fusion methodology	Application
Current sensor, AE	BN	Tool wear diagnosis
Current sensor, accelerometer	BN	Tool wear diagnosis
	BN	Surface roughness prediction
Accelerometer, AE	NN	Tool wear diagnosis
Accelerometer, vision system	NN	Tool wear diagnosis
Dynamometer, AE	-	Tool breakage detection
	NN	Tool wear diagnosis
Dynamometer, AE, accelerometer	NN	Surface roughness prediction
Dynamometer, accelerometer	NN	Tool wear diagnosis
	NN	Surface roughness prediction
	NN	Prediction of dimensional part accuracy
Dynamometer, thermistors	NN	Prediction of dimensional part accuracy
Dynamometer, accelerometer, spindle current, voltage sensor, sound pressure level	NN	Tool wear diagnosis

Abellan-Nebot, J. V., & Subirón, F. R. (2010) *The International Journal of Advanced Manufacturing Technology*, 47(1-4), 237-257



Fujishima M. et al. (2017) *24th Conference on Life Cycle Engineering*, Procedia CIRP 61, 796-799

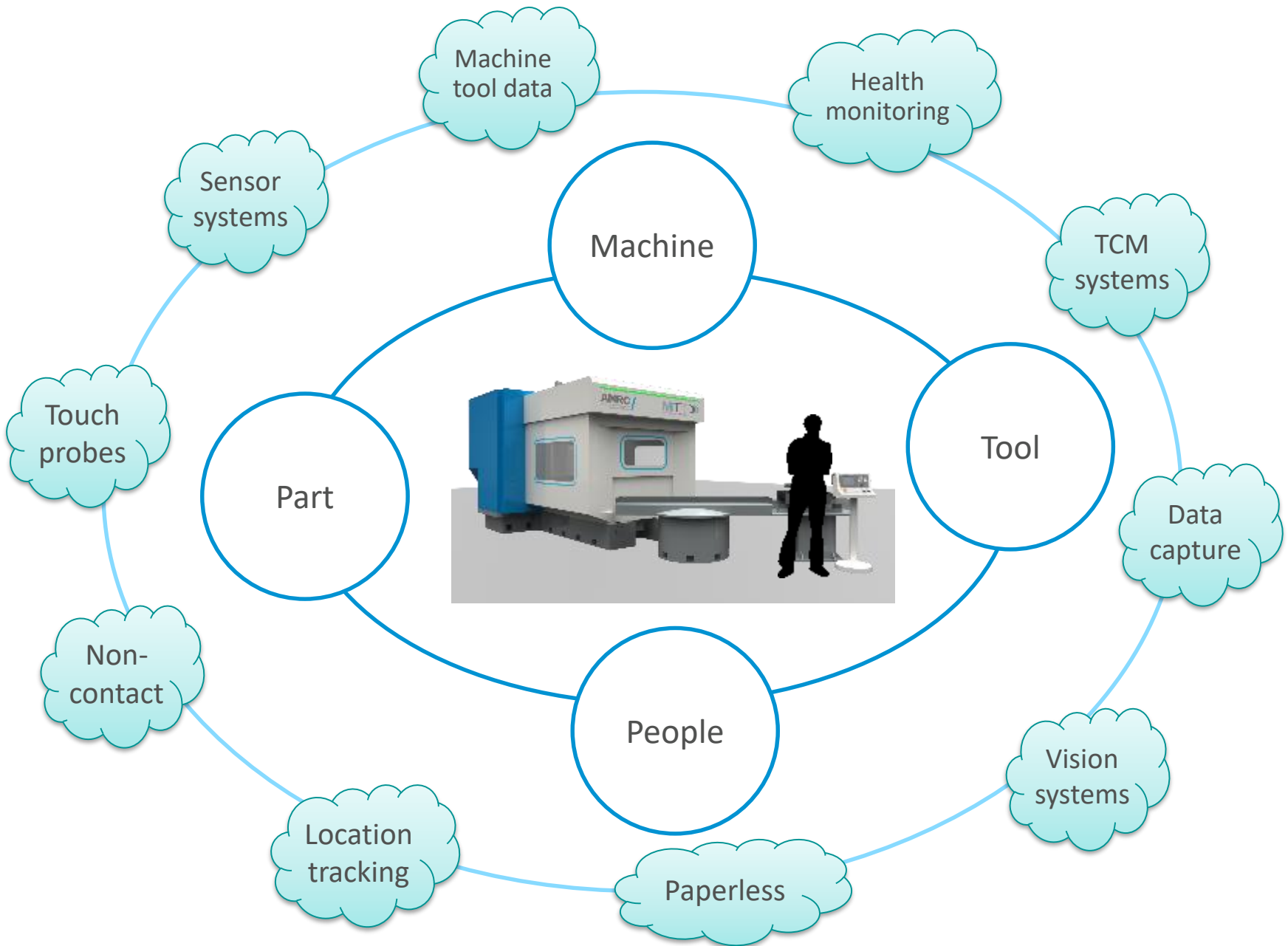
Industry

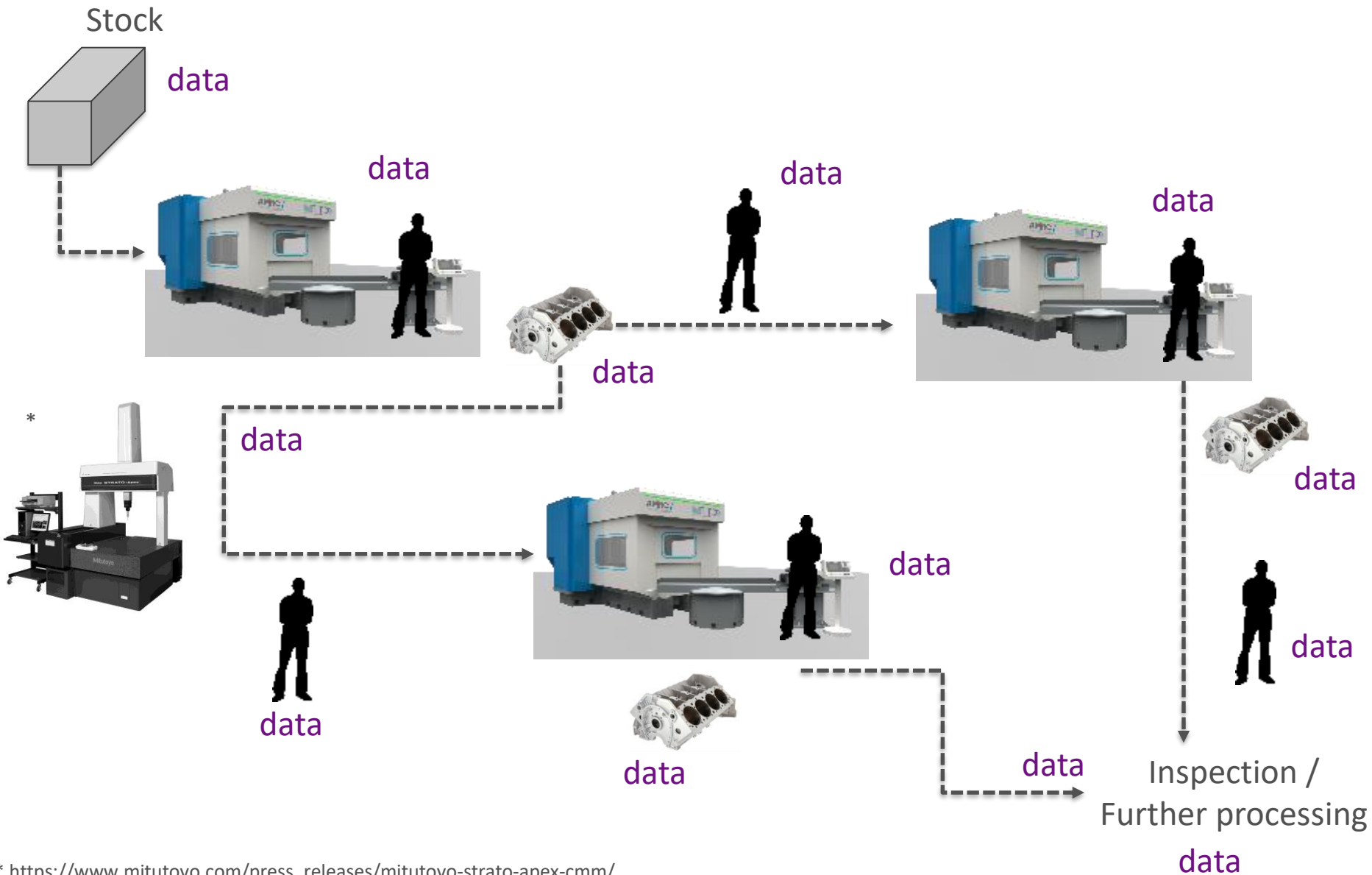


SIEMENS
Analyze MyCondition

CELOS BY DMG MORI







* https://www.mitutoyo.com/press_releases/mitutoyo-strato-apex-cmm/

Contents

- On-machine inspection
- Tool condition monitoring
- Machine health verification
- Process health
- Future thoughts

On-machine inspection

- inspection of a part or feature without removing the part from the machine tool

On-machine inspection

Manual gauges



Roughness gauge probe



Blum TC63-RG roughness gauge

Touch probes



Is this in the right place? How big is this thing? How good is it's surface?

Scanning probes



Optical scans

Vision systems

Tool condition monitoring

- *continually verifying that the tool condition is within the bounds of the process*

Tool condition monitoring

Use-case: Is my tool still OK? Has it worn beyond acceptable limits? Is it about to break or has it broken already?

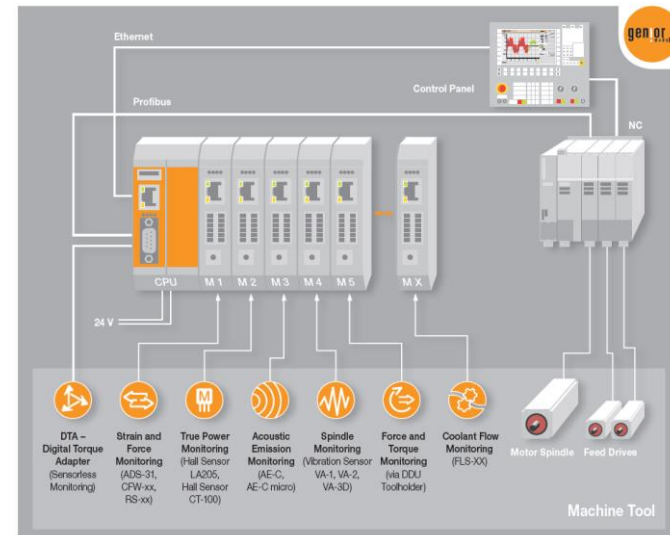
TCM systems

Advantages

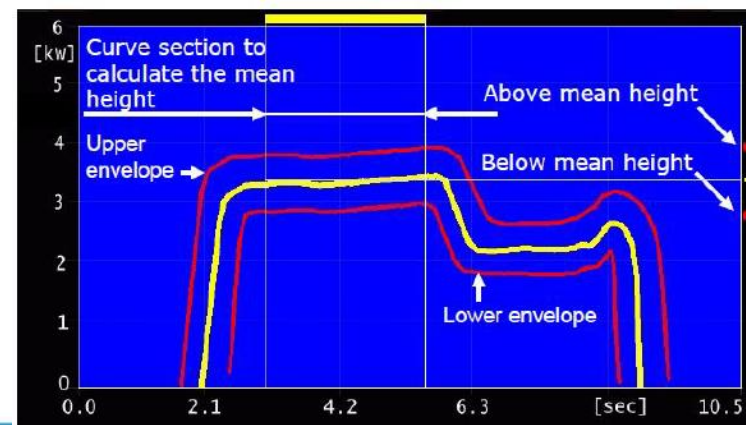
- Many commercial-ready systems available
- Can inform on process condition
- Auto stop of machine if tool breaks
- Machine health often covered

Disadvantages

- Add-on item – additional expense
- Learning time
- Tool wear not always covered



For example, the ARTIS Genior system



Nordmann SEM system screen grab

Tool condition monitoring

Use-case: Is my tool still OK? Has it worn beyond acceptable limits? Is it about to break or has it broken already?

Academic view

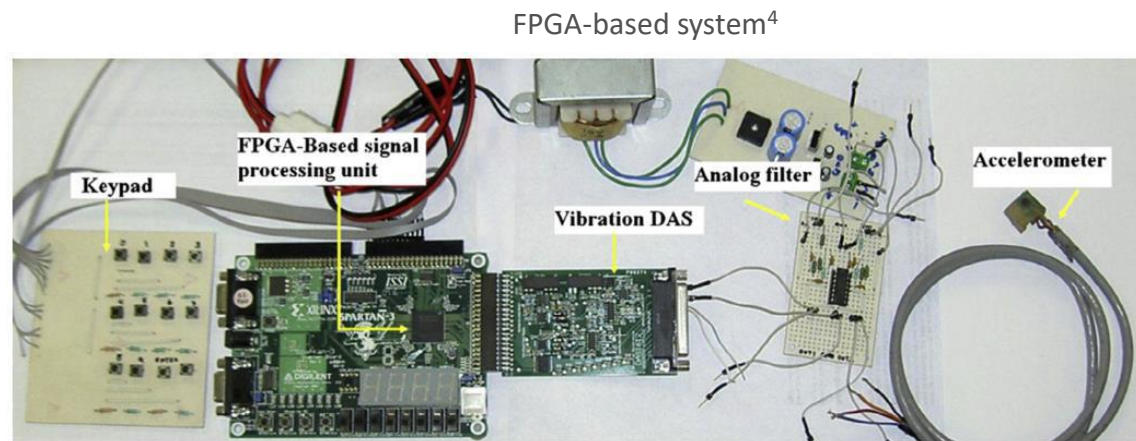
Direct vs Indirect¹

Actual vs. Inferred measurements

- Microscope for actual
 - Accurate
- Sensors for indirect
 - Non-intrusive

Indirect

- Forces – dynos²
- Acoustic emission
- Vibration³
- Machine tool data (eg spindle power)
- Machine learning features heavily



1 – Ambhore N et al. *Materials Today: Proceedings*, 2015, pp. 3419–3428.

2 – Huang PTB et al. *Appl Soft Comput J* 2015; 37: 114–124.

3 – Krishnakumar P et al. *Procedia Comput Sci* 2015; 50: 270–275.

4 – Sevilla-Camacho PY et al. *Measurement* 2015; 64: 81–88.

Machine health verification

- *verifying before/during/after machining that the machine tool is performing within the bounds of the process*

Machine health verification

Use-case: Is this machine tool ready to go? Will it make a good part? Is it in need of servicing, either now or in the near future?

Probe tool checks

Advantages

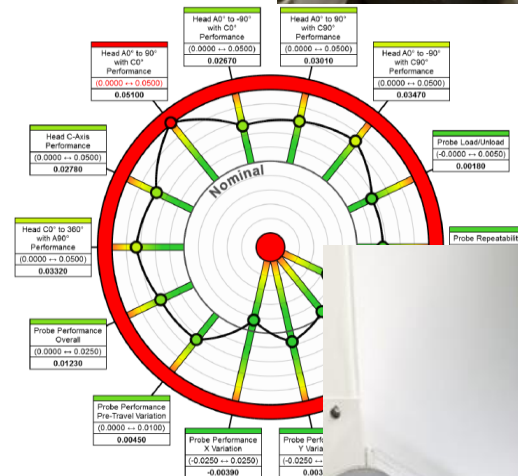
- Probe tool usually already available
- Automated
- Data logging
- Start of shift
- Can use machine bed as artefact¹

Disadvantages

- Time consuming – machine tool not cutting
- Not a diagnosis
- Reliant on probe accuracy



www.renishaw.com



metsoftpro.com

www.industry.siemens.com



Machine health verification

Use-case: Is this machine tool ready to go? Will it make a good part? Is it in need of servicing, either now or in the near future?

Spindle health

Advantages

- Can often be permanently mounted in machine
- Rapid verification of spindle runout
- Automated
- Data logging

Disadvantages

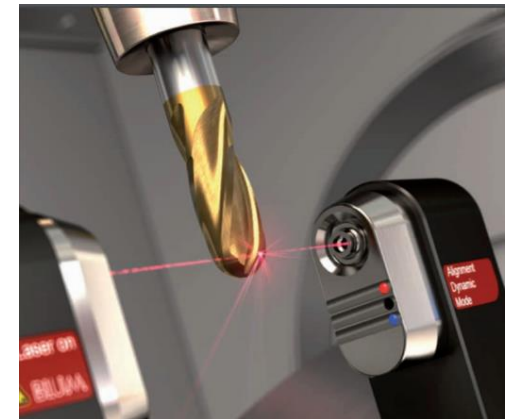
- Additional hardware often required
- Can be expensive
- Machine not cutting....



www.ibspe.com



www.apisensor.com



www.blum-novotest.com

Machine health verification

Use-case: Is this machine tool ready to go? Will it make a good part? Is it in need of servicing, either now or in the near future?

Laser measurement

Advantages

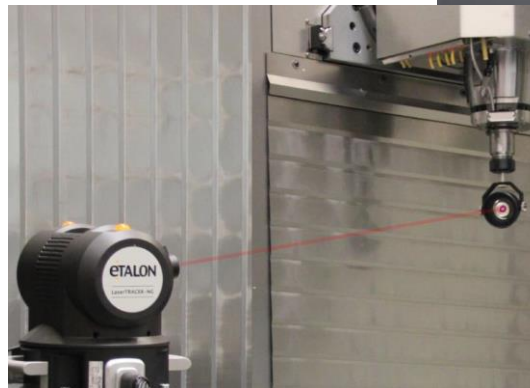
- Highly accurate measurement of positioning performance
- Large volumes covered

Disadvantages

- Expensive hardware
- Cannot be fully automated
- Experience required to set up and diagnose



www.renishaw.com



www.etalon-ag.com



www.etalon-ag.com

Machine health verification

Use-case: Is this machine tool ready to go? Will it make a good part? Is it in need of servicing, either now or in the near future?

Sensor systems

Advantages

- Rapid check of machine health
- Indication of change to machine health
- Unobtrusive sensors

Disadvantages

- Diagnosis of error source needs many sensors
- Sensors need to be retrofitted

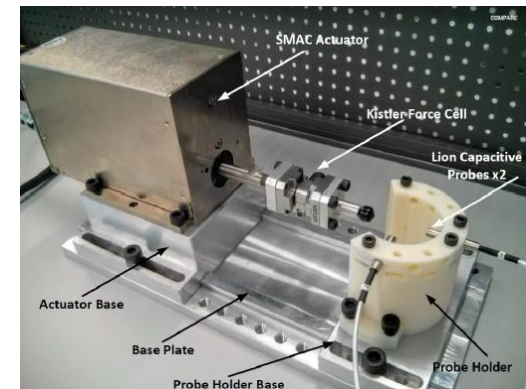
Academic work

Multi-sensor box¹

- Degradation of linear axes
- Laser interferometer for reference
- Promising results

Auto tap test²

- Diagnosis of error source needs many sensors
- Sensors need to be retrofitted

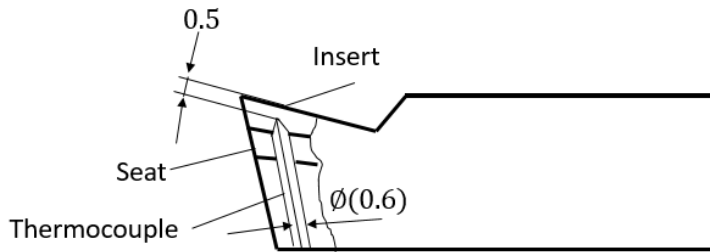


1 – G. W. Vogl et al., *Procedia Manufacturing*, vol. 5, pp. 621-633, 2016.
2 – AMRC with Boeing, “ABG109 - Self-actuated automated system for impact testing at high rotating speeds,” 2016.

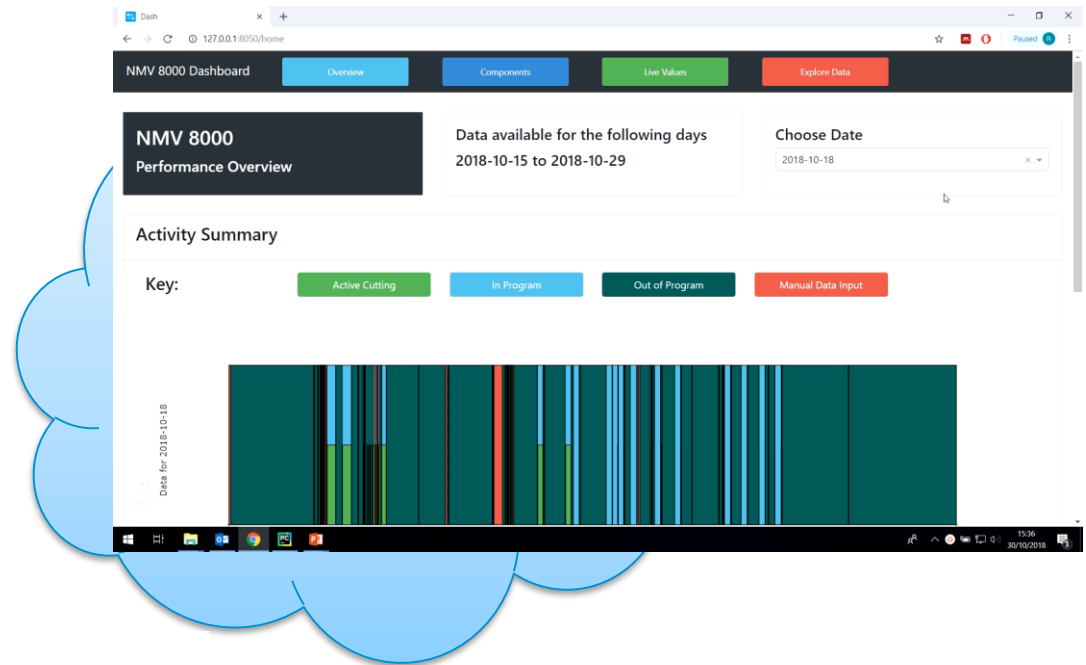
Process health

- continuous monitoring of performance indicators to verify that the process is within acceptable bounds

Process health



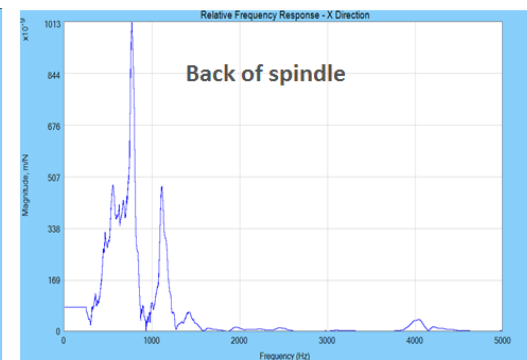
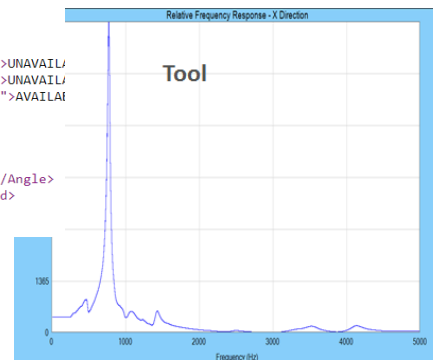
Thermocouple embedded in tool insert¹



```

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</Samples>
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```



FRF measurements for remote accelerometer²

- 1 – AMRC with Boeing, “ABG2473B – Temperature measurement in milling”, 2018.
- 2 – AMRC with Boeing, “ABG113 – Non-intrusive sensing system”, 2016

Future thoughts

Process version control

Version control is not new – very common in software development and server-based document storage.

Can it be applied to all shop floor processes?

- NC programs
- Manufacturing documents
- Drawings
- People?
- Raw stock
- Tools
- Calibration certificates

Complete data trail for all processes

Machine tool servitisation

Power by the hour



A service built around the asset of a **jet engine**

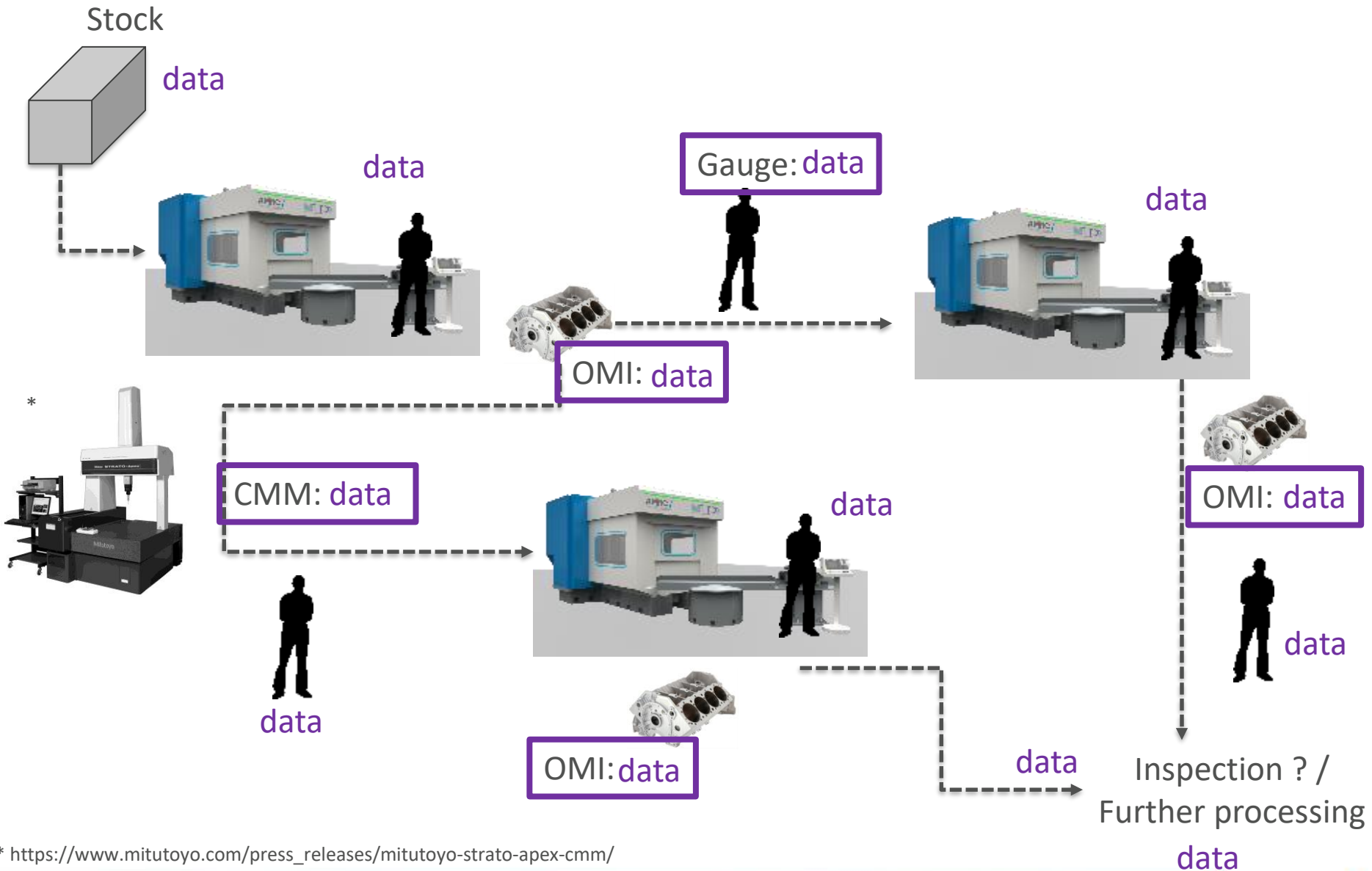
Servitising a machine tool



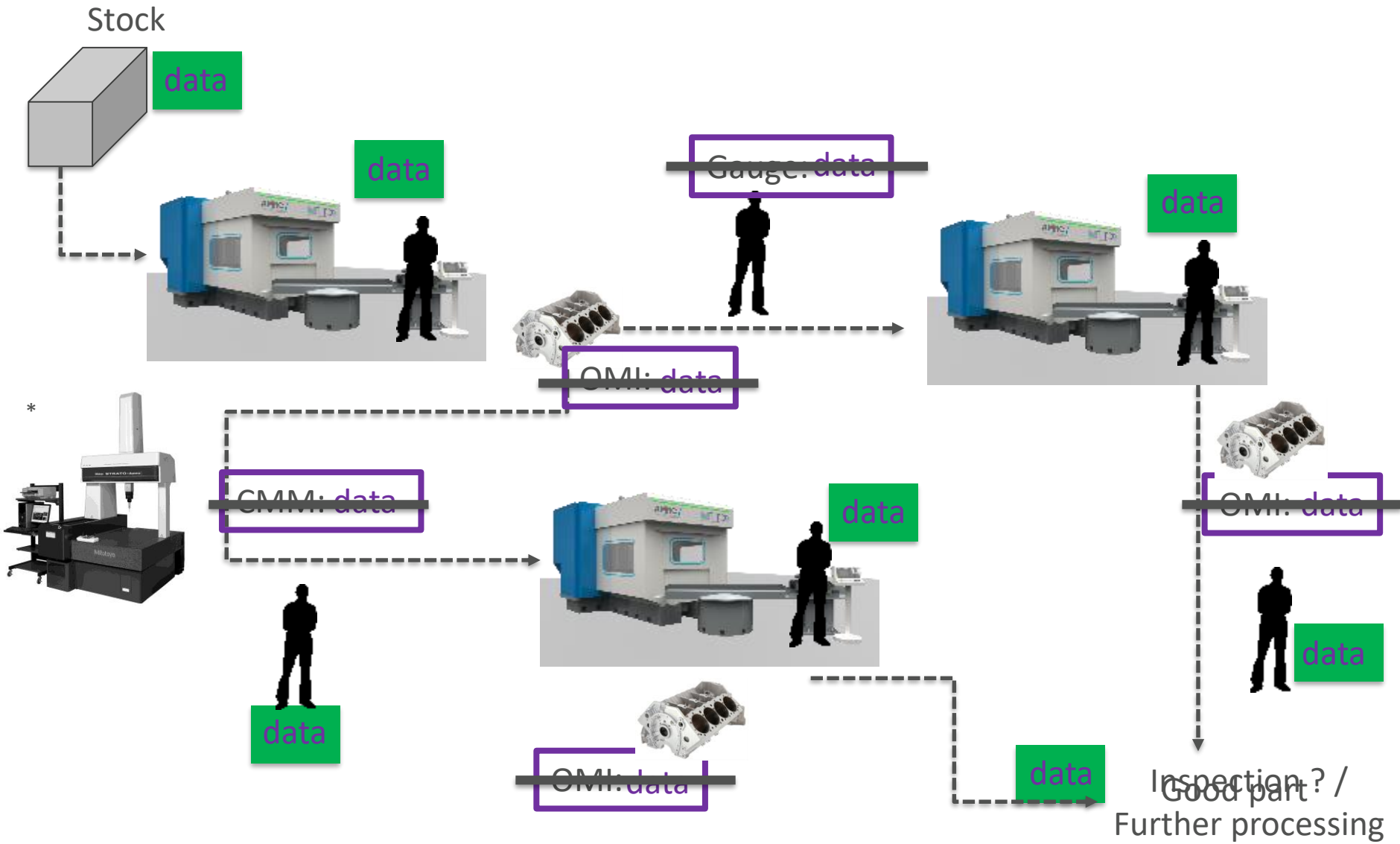
A service built around the asset of a **machine tool**

The following slides were not used in the presentation at the conference, but were available for discussion.

Non-geometric validation



Non-geometric validation



* https://www.mitutoyo.com/press_releases/mitutoyo-strato-apex-cmm/

Non-geometric validation

Can we validate a part without doing any traditional inspection?

Use of sensor data (and others?) to inform on process health.

If no significant change to the data, why would the part not conform?

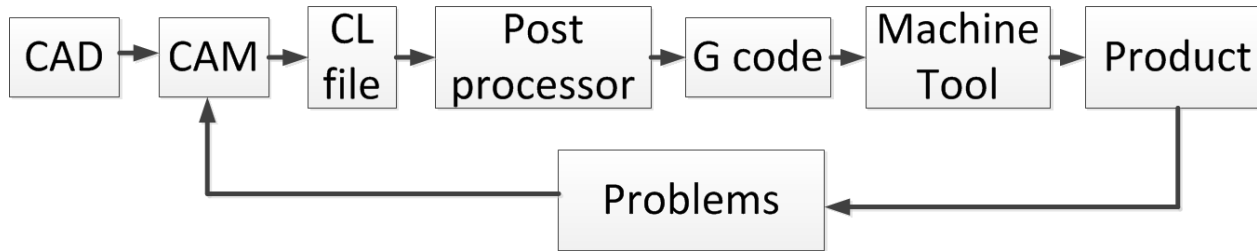
Only inspect when absolutely necessary – *Inspection by Exception*

System will need to learn what good parts look like, from a data perspective

Human input still needed as system will continue to learn – correction of false positives / negatives

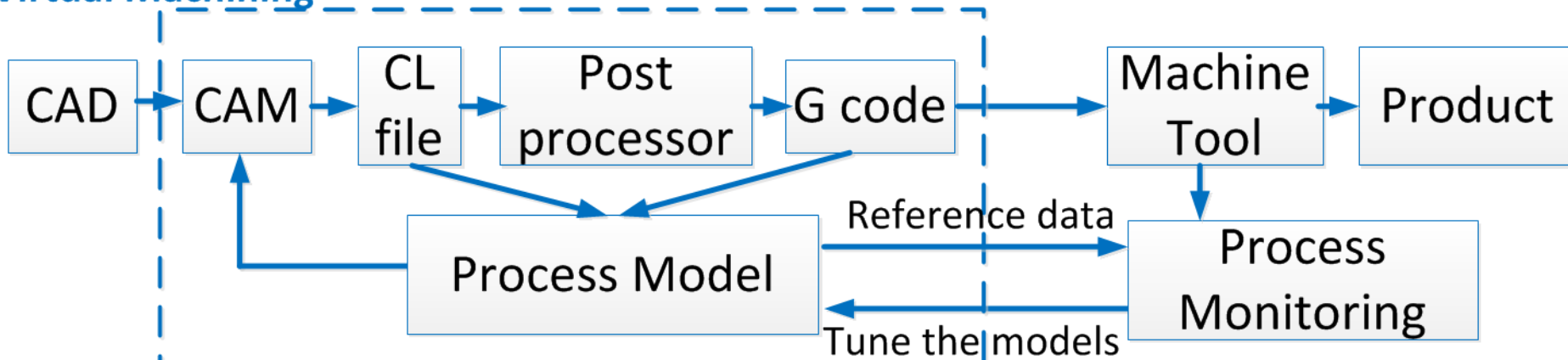
Sample inspection still needed?

Virtual machining and Optimisation



- Torque/Power limits
- Chatter Vibrations
- High Form Errors
- Part distortions
- Tool Breakage

Virtual Machining





The
University
Of
Sheffield.

Thank you.

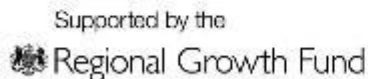
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Twitter: @theAMRC



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